## Welcome to the webinar René Descartes would code a Rover if he could



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## 埌 Texas Instruments

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## Overview:

- René Descartes brief introduction
- Main ideas and works
- Focus on Light refraction
- Descartes would code a Rover


## Hardware and software:



Ti-innovator Hub

Ti 83 premium CE Python Edition


## René Descartes



## A crucial meeting



## 1637

Discourse on the Method of Rightly Conducting the Reason, and Searching for Truth in the Sciences



1643
Marin Mersenne

Girard Desargues -


 cio io c xxxvi. Anec Privilege.

## Four main precepts

■ Accept nothing as true that is not self-evident.

■ Divide problems into their simplest parts.

- Solve problems by proceeding from simple to complex.

■ Recheck the reasoning.

## Filter of TRUE



## Construction of a square root



$$
G I=\sqrt{G H}
$$

Link to a translated version of La Géométrie


$$
\begin{aligned}
& O M=O N+N M \\
& \text { cas } N M=\sqrt{b^{2}+\frac{O^{2}}{4} \quad \text { anol } \quad O N=\frac{1}{2} a}
\end{aligned}
$$

hence

$$
O M=\frac{a}{2}+\sqrt{b^{2}+\frac{a^{2}}{4}}
$$

It follows

$$
\begin{aligned}
O M^{2} & =\frac{a^{2}}{4}+b^{2}+\frac{a^{2}}{4}+a \sqrt{b^{2}+\frac{a^{2}}{5}} \\
O M^{2} & =\frac{0^{3}}{2}+b^{2}+a \sqrt{b^{2}+\frac{4^{2}}{5}} \\
\therefore O M^{2} & =a\left(\frac{a}{2}+\sqrt{b^{2}+\frac{a^{2}}{b}}\right)+b^{2} \\
\therefore O M^{2} & =a \times O M+b^{2}
\end{aligned}
$$

then if we set $z=0 n: z^{2}=a z+b^{2}$

$$
z^{2}=a z+b^{2}(a>0)
$$



$$
\mathrm{z}=O M
$$




## Snell-Descartes law <br> -Law of refraction-



$$
\frac{\sin \left(\theta_{2}\right)}{\sin \left(\theta_{1}\right)}=\frac{v_{2}}{v_{1}}=\frac{n_{1}}{n_{2}}
$$

## Descartes would code a Rover



$Q \Leftrightarrow \Delta \square \quad \vdots$
vitta
science

## Programming

Get to the programming interface you want by clicking on the cards．


## Problem: Recognize a right angle on a colorized path

Sub-problems:

- Validate the path color.
- Stop when the color isn't the same anymore.
- Rotate $90^{\circ}$.
- Continue straight forward if the color is correct.


Preamble activity:

- Write a Python function that make the Rover draw a right triangle


| ( EDITOR: PPARK |  |  |
| :---: | :---: | :---: |
| Drive I/O Settings Commands |  |  |
|  |  |  |
| 2: for | ard(distance) | unit |
| 3: bac | ward(distance) | unit |
| 4: lef | (angle) | degrees |
| 5:rig | ( (angle) | degrees |
| 6:stop() |  |  |
| 7:resume() |  |  |
| 8:sta | (time) | seconds |
| 9: to_xy ( $x, y$ ) |  |  |
| 0 $\downarrow$ to_ | olar(r, theta) | < degrees |
| Esc | Modul |  |

- Write a Python function that make the Rover draw a right triangle


Problem: Recognize a right angle on a colorized path

Sub-problems

- Validate the path color.


```
EDITEUR : COUL1
LIGNE DU SCRIPT 0017
def reco():
*global r,g,b
    *a=0
* while a!=1:
**ru.color_off()
**r=ru.red_measurement ()
**.g=rv.green_measurement()
* b=ru.blue_measurement()
*rv.color_rgb(r,g,b)
**avint(input("cogileur ok?"))
**sleep(3)
**ru.color_off()
* return r,g,b
def repro():
*r,g,b=reco()
*a=int(input("reproduire la cou
- if leur?"))
* if a==1:
*ru.color_rgb(r,g,b)
**sleep(3)
**ru.color_off()
    else:
**ru.color_off()
Fns.-.|a A #|Outils| Exéc |Script
```

Problem: Recognize a right angle on a colorized path

```
Sub-problems
```

- Validate the path color.
- Rotate $90^{\circ}$.


Problem: Recognize a right angle on a colorized path

Sub-problems:

- Validate the path color.
- Rotate $90^{\circ}$.

－Validate the path color．
- Rotate $90^{\circ}$ ．
－Continue straight forward if the color is correct．


```
        ÉDITEUR : COUL1
        LIGNE DU SCRIPT 003:
def avance(d):
reco()
*r1=r
    g1=g
    b1=b
    *while r1>=0.8粦r and r1<=1.2* r
                and g1>=0.8*g and g1<=1.2*
                g and b1>=0.8*⿱⿱㇒⿻丷木心
        **:
***rv.forward(10)
* r1=rv.red_measurement()
**g1=rv.green_measurement ()
**bl=rv.blue_measurement()
*rv.stop()
*ru.backward(0.8)
*
*if d=="d":
*.rv.right(90)
*else:
*-*rv.left(90)
*rv.forward(0.3)
Fns...|a A #|Outils| Exéc |Script
```


## How to register for a webinar

- https://tiedtech.yello.co/external/events cent ral


